

orxBODY structure

Summary

Body

```
[BodyTemplate]
PartList          = BodyPartTemplate1#BodyPartTemplate2#...
AllowGroundSliding = <bool>
AngularDamping     = <float>
CustomGravity      = <vector>
Dynamic            = <bool>
FixedRotation      = <bool>
HighSpeed          = <bool>
Inertia             = <float>
LinearDamping       = <float>
Mass                = <float>
```

BodyPart

Sphere

```
[BodyPartSphereTemplate]
Type          = sphere
Center        = <vector> | full
Radius        = <float> | full
CheckMask     = <16b flags>
SelfFlags     = <16b flags>
Density       = <float>
Friction      = <float>
Restitution   = <float>
Solid         = <bool>
```

Box

```
[BodyPartBoxTemplate]
Type          = box
TopLeft       = <vector> | full
BottomRight   = <vector> | full
CheckMask     = <16b flags>
SelfFlags     = <16b flags>
Density       = <float>
Friction      = <float>
Restitution   = <float>
```

Solid = `<bool>`

Mesh (polygon)

```
[BodyPartMeshTemplate]
Type      = mesh
VertexList = <vector>#<vector>#...
CheckMask  = <16b flags>
SelfFlags  = <16b flags>
Density    = <float>
Friction   = <float>
Restitution = <float>
Solid      = <bool>
```

Details

Body

Here's a list of the available properties for an `orxBODY` structure:

- **PartList**: List of all the parts that will compose a body. Up to 8 parts can be defined for a single body. This property *needs* to be defined if you want it to collide with other bodies.
- **AllowGroundSliding**: If set to false on a dynamic object, it will prevent it from sliding on static slopes of more than 45°. This only works with a vertical top-down gravity. By default its value is `true`.
- **AngularDamping**: Damping of angular velocity for this body. By default its value is 0.0, which means no damping.
- **CustomGravity**: Defines a gravity vector to use for this body instead of the world's one. By default it doesn't exist, which means world's gravity will be used for this body.
- **Dynamic**: Defines if this body should be dynamic or static. If your object is expected to move, this property should be set to `true`. Static bodies can't collide with other static bodies. By default, its value is `false` (ie. static).
- **FixedRotation**: Defines if your dynamic object is allowed to rotate as a result of collision forces. By default its value is `false` which means it can rotate freely.
- **HighSpeed**: For high velocity objects (like bullets), this property should be set to `true` to avoid collision errors. However, every object flagged as HighSpeed will cost more when processed by the physics engine. By default its value is `false`.
- **Inertia**: Defines an inertia value for this body. By default its value is 0.0.
- **LinearDamping**: Damping of speed (linear velocity) for this body. By default its value is 0.0, which means no damping.
- **Mass**: Defines a mass, in kg, for this body. If parts are defined, the mass will be overridden by an automatically calculated value based of parts' sizes and positions.

BodyPart

Common

Here's a list of the available properties for all types of body parts:

- **Type:** Defines the type of the body part. Available types are **sphere**, **box** and **mesh** (ie. convex polygon). This property *needs* to be defined.
- **CheckMask/SelfFlags:** Both properties are flags expressed on 16bits. The **SelfFlags** defines this part identity whereas the **CheckMask** defines which parts are allowed to collide with it. For a collision to happen between two parts the expressions (**Part1.CheckMask & Part2.SelfFlags**) and (**Part2.CheckMask & Part1.SelfFlags**) have both to evaluate to **true**. NB: Two parts of the same body won't collide whichever **CheckMask/SelfFlags** they have.¹⁾
- **Density:** Defines the density of this part. Its default value is 0.0, which means it doesn't have any influence on the body's mass.
- **Friction/Restitution:** Define the friction and restitution of this part, usually between 0.0 and 1.0.²⁾ By default both their values are 0.0.
- **Solid:** Defines if this part is solid or not. Only solid parts will trigger a reaction on their body when colliding with others. By default its value is **false** which means the collision info will be signaled through events, but the physics simulation of this body won't be automatically affected by it.

Sphere

Here's a list of the available properties only available to sphere parts:

- **Center:** Defines the center of the sphere (in 2D it's a circle, of course) in the parent's space (ie. in object's space). By default its value is **full** which means the center will match the object's one (ie. the center of its current graphic).
- **Radius:** Defines the radius of the sphere (or 2D circle). By default its value is **full** which means the sphere's radius will match the biggest dimension of the parent object. You can find an example in the [spawner tutorial](#)³⁾.

Box

Here's a list of the available properties only available to box parts:

- **TopLeft/BottomRight:** Define the extrema of the box (in 2D it's a rectangle, of course) in the parent's space (ie. in object's space). By default their values are **full** which means **TopLeft** and **BottomRight** will match the full rectangle defined by the parent object's current graphic. You can find an example in the [physics tutorial](#).

Mesh (polygon)

Here's a list of the available properties only available to mesh⁴⁾ parts:

- **VertexList:** Provides a list of vertex coordinates in parent object's space. The resulting

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polygon *needs* to be convex. Up to 8 vertices can be defined and they *have to be entered clockwise*. You can find an example in the [spawner tutorial](#)⁵⁾.

1)

Check [Box2D wiki](#) for more information on filtering

2)

Check [Box2D wiki](#) for more information on friction/restitution

3)³⁾ 5)

, by looking directly at the config files as they're not covered in the wiki

4)

convex polygon

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